

## Test CODE Example

### 1、Display with Arduino:

Now we will show how to use the Arduino (ATMega 168) to control the TFT LCD module. To have a quicker refresh rate, we use the 16bit mode for LCD, it's two times faster than 8 bit mode.

#### Connect the pins to Arduino first:

DB0-DB16 to pin D0-D13, pin A0-A1 of Arduino  
RESET to A2  
CS to A3  
WR to A4  
RS to A5

All the data pins of Arduino is used ....So, we just can connect the RD to 3.3V ....We don't used it because we don't need to read back the data from the screen.

#### Connect the power pins: LCD-A to 3.3V, VCC to 5V , GND to GND

Note that the LCD is use the 3.3V voltage level , so if you want to connect the 5V Arduino pins to it , you need add a resister about 20K to reduce voltage. We use the 3.3V Arduino Pro which work in 8M , so we connect the pins directly — this is why we used 16 bit mode, 8 bit mode is too slow to refresh the screen.

Download the Demo code below into the controller :

```
define LCD_RS 19
#define LCD_REST 16
#define LCD_WR 18
#define LCD_CS 17

void main_Write_COM(int DH)
{
    unsigned char i;
    int temp;
    digitalWrite(LCD_RS,LOW);
    digitalWrite(LCD_CS,LOW);
    for(i=0;i<16;i++)
    {
        temp=(DH&0x01);
        if(temp)
            digitalWrite(i,HIGH);
```

```

    else
        digitalWrite(i,LOW);
        DH=DH>>1;
    }
    digitalWrite(LCD_WR,LOW);
    digitalWrite(LCD_WR,HIGH);
    digitalWrite(LCD_CS,HIGH);
}

void main_Write_DATA(int DH)
{
    unsigned char i;
    int temp;
    digitalWrite(LCD_RS,HIGH);
    digitalWrite(LCD_CS,LOW);
    for(i=0;i<16;i++)
    {
        temp=(DH&0x01);
        if(temp)
            digitalWrite(i,HIGH);
        else
            digitalWrite(i,LOW);
        DH=DH>>1;
    }
    digitalWrite(LCD_WR,LOW);
    digitalWrite(LCD_WR,HIGH);
    digitalWrite(LCD_CS,HIGH);
}

void main_W_com_data(int com1,int dat1)
{
    main_Write_COM(com1);
    main_Write_DATA(dat1);
}

void address_set(unsigned int x1,unsigned int y1,unsigned int x2,unsigned int y2)
{
    main_W_com_data(0x0002,x1>>8);      // Column address start2
    main_W_com_data(0x0003,x1);          // Column address start1
    main_W_com_data(0x0004,x2>>8);      // Column address end2
    main_W_com_data(0x0005,x2);          // Column address end1
    main_W_com_data(0x0006,y1>>8);      // Row address start2
    main_W_com_data(0x0007,y1);          // Row address start1
    main_W_com_data(0x0008,y2>>8);      // Row address end2
}

```

```

    main_W_com_data(0x0009,y2);      // Row address end1
    main_Write_COM(0x0022);

}

void main_init(void)
{
    digitalWrite(LCD_REST,HIGH);
    delay(5);
    digitalWrite(LCD_REST,LOW);
    delay(10);
    digitalWrite(LCD_REST,HIGH);
    delay(20);

    // VENDOR
    main_W_com_data(0x0046,0x00A4);
    main_W_com_data(0x0047,0x0053);
    main_W_com_data(0x0048,0x0000);
    main_W_com_data(0x0049,0x0044);
    main_W_com_data(0x004a,0x0004);
    main_W_com_data(0x004b,0x0067);
    main_W_com_data(0x004c,0x0033);
    main_W_com_data(0x004d,0x0077);
    main_W_com_data(0x004e,0x0012);
    main_W_com_data(0x004f,0x004C);
    main_W_com_data(0x0050,0x0046);
    main_W_com_data(0x0051,0x0044);

    //240x320 window setting
    main_W_com_data(0x0002,0x0000); // Column address start2
    main_W_com_data(0x0003,0x0000); // Column address start1
    main_W_com_data(0x0004,0x0000); // Column address end2
    main_W_com_data(0x0005,0x00ef); // Column address end1
    main_W_com_data(0x0006,0x0000); // Row address start2
    main_W_com_data(0x0007,0x0000); // Row address start1
    main_W_com_data(0x0008,0x0001); // Row address end2
    main_W_com_data(0x0009,0x003f); // Row address end1

    // Display Setting
    main_W_com_data(0x0001,0x0006); // IDMON=0, INVON=1, NORON=1, PTLON=0
    main_W_com_data(0x0016,0x00C8); // MY=0, MX=0, MV=0, ML=1, BGR=0, TEON=0
    0048
    main_W_com_data(0x0023,0x0095); // N_DC=1001 0101

```

```

main_W_com_data(0x0024,0x0095); // PI_DC=1001 0101
main_W_com_data(0x0025,0x00FF); // I_DC=1111 1111

main_W_com_data(0x0027,0x0002); // N_BP=0000 0010
main_W_com_data(0x0028,0x0002); // N_FP=0000 0010
main_W_com_data(0x0029,0x0002); // PI_BP=0000 0010
main_W_com_data(0x002a,0x0002); // PI_FP=0000 0010
main_W_com_data(0x002C,0x0002); // I_BP=0000 0010
main_W_com_data(0x002d,0x0002); // I_FP=0000 0010

main_W_com_data(0x003a,0x0001); // N_RTN=0000, N_NW=001      0001
main_W_com_data(0x003b,0x0000); // P_RTN=0000, P_NW=001
main_W_com_data(0x003c,0x00f0); // I_RTN=1111, I_NW=000
main_W_com_data(0x003d,0x0000); // DIV=00
delay(1);
main_W_com_data(0x0035,0x0038); // EQS=38h
main_W_com_data(0x0036,0x0078); // EQP=78h
main_W_com_data(0x003E,0x0038); // SON=38h
main_W_com_data(0x0040,0x000F); // GDON=0Fh
main_W_com_data(0x0041,0x00F0); // GDOFF

// Power Supply Setting
main_W_com_data(0x0019,0x0049); // CADJ=0100, CUADJ=100, OSD_EN=1 ,60Hz
main_W_com_data(0x0093,0x000F); // RADJ=1111, 100%
delay(1);
main_W_com_data(0x0020,0x0040); // BT=0100
main_W_com_data(0x001D,0x0007); // VC1=111      0007
main_W_com_data(0x001E,0x0000); // VC3=000
main_W_com_data(0x001F,0x0004); // VRH=0011

//VCOM SETTING
main_W_com_data(0x0044,0x004D); // VCM=101 0000  4D
main_W_com_data(0x0045,0x000E); // VDV=1 0001    0011
delay(1);
main_W_com_data(0x001C,0x0004); // AP=100
delay(2);

main_W_com_data(0x001B,0x0018); //  GASENB=0,   PON=0,   DK=1,   XDK=0,
VLCD_TRI=0, STB=0
delay(1);
main_W_com_data(0x001B,0x0010); //  GASENB=0,   PON=1,   DK=0,   XDK=0,
VLCD_TRI=0, STB=0
delay(1);
main_W_com_data(0x0043,0x0080); //set VCOMG=1

```

```

delay(2);

// Display ON Setting
main_W_com_data(0x0090,0x007F); // SAP=0111 1111
main_W_com_data(0x0026,0x0004); //GON=0, DTE=0, D=01
delay(1);
main_W_com_data(0x0026,0x0024); //GON=1, DTE=0, D=01
main_W_com_data(0x0026,0x002C); //GON=1, DTE=0, D=11
delay(1);
main_W_com_data(0x0026,0x003C); //GON=1, DTE=1, D=11

// INTERNAL REGISTER SETTING
main_W_com_data(0x0057,0x0002); // TEST_Mode=1: into TEST mode
main_W_com_data(0x0095,0x0001); // SET DISPLAY CLOCK AND PUMPING CLOCK
TO SYNCHRONIZE
main_W_com_data(0x0057,0x0000); // TEST_Mode=0: exit TEST mode
//main_W_com_data(0x0021,0x0000);
main_Write_COM(0x0022);

}

void Pant(unsigned int color)
{
int i,j;
address_set(0,0,239,319);

for(i=0;i<320;i++)
{
    for (j=0;j<240;j++)
    {
        main_Write_DATA(color);
    }
}
}

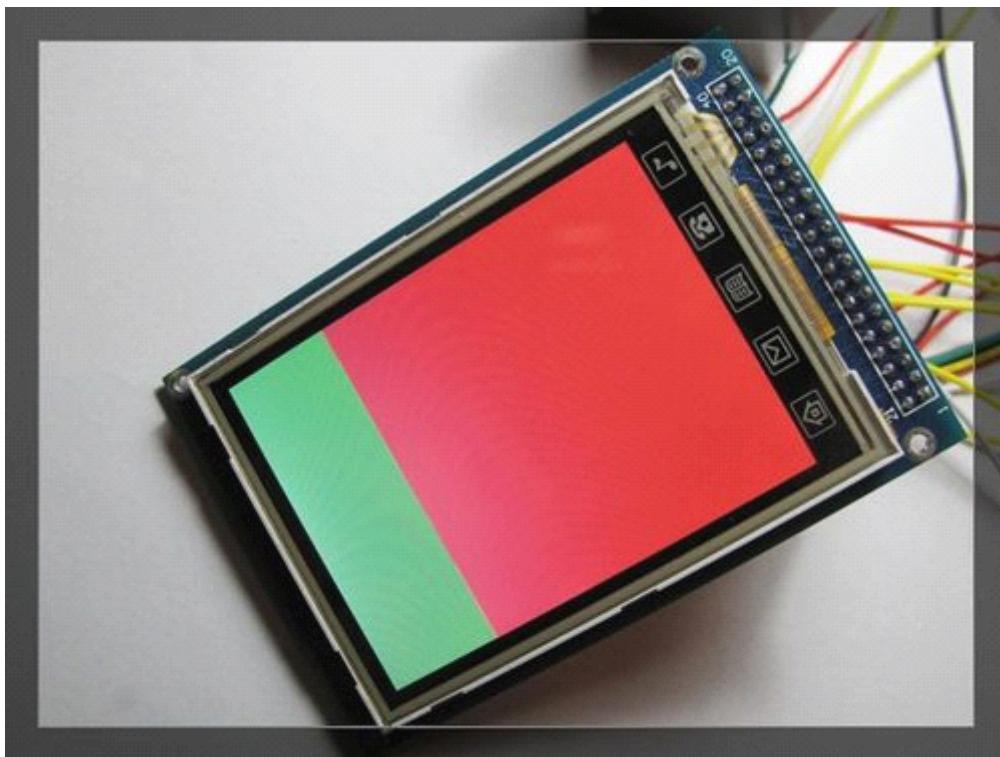
void setup()
{
unsigned char p;
for(p=0;p<20;p++)
{
pinMode(p,OUTPUT);
}
main_init();
}

```

```
}

void loop()
{
    Pant(0xf800); //Red
    delay(1000);
    Pant(0X07E0); //Green
    delay(1000);
    Pant(0x001f); //Blue
    delay(1000);
}
```

OK, reset your board, you can find the screen will display in red, green and blue.



## 2、Demo code for TFT LCD

Here is a demo code that use the STC 51 MCU to drive the module. The controller communicate with the screen in 16bit parallel mode , and use 4 more pins for timing and mode control.

The code display a image of the image[3200] in the module .

**First, Initial the TFT screen:**

```

void LCD_Init(void)
{
    LCD_REST=1;
    delayms(5);
    LCD_REST=0;
    delayms(5);
    LCD_REST=1;
    delayms(5);

    LCD_CS =0; //enable cs
    //***** Start Initial Sequence *****/
    LCD_Write_COM(0x00,0xE5); LCD_Write_DATA(0x78,0xF0); // set SRAM internal
timing
    LCD_Write_COM(0x00,0x01); LCD_Write_DATA(0x01,0x00); // set SS and SM bit
    LCD_Write_COM(0x00,0x02); LCD_Write_DATA(0x07,0x00); // set 1 line inversion
    LCD_Write_COM(0x00,0x03); LCD_Write_DATA(0x10,0x30); // set GRAM write
direction and BGR=1.
    LCD_Write_COM(0x00,0x04); LCD_Write_DATA(0x00,0x00); // Resize register
    LCD_Write_COM(0x00,0x08); LCD_Write_DATA(0x02,0x07); // set the back porch
and front porch
    LCD_Write_COM(0x00,0x09); LCD_Write_DATA(0x00,0x00); // set non-display area
refresh cycle ISC[3:0]
    LCD_Write_COM(0x00,0xA); LCD_Write_DATA(0x00,0x00); // FMARK function
    LCD_Write_COM(0x00,0x0C); LCD_Write_DATA(0x00,0x00); // RGB interface
setting
    LCD_Write_COM(0x00,0xD); LCD_Write_DATA(0x00,0x00); // Frame marker
Position
    LCD_Write_COM(0x00,0xF); LCD_Write_DATA(0x00,0x00); // RGB interface
polarity
    //*****Power On sequence*****//
    LCD_Write_COM(0x00,0x10); LCD_Write_DATA(0x00,0x00); // SAP, BT[3:0], AP,
DSTB, SLP, STB
    LCD_Write_COM(0x00,0x11); LCD_Write_DATA(0x00,0x07); // DC1[2:0], DC0[2:0],
VC[2:0]
    LCD_Write_COM(0x00,0x12); LCD_Write_DATA(0x00,0x00); // VREG1OUT voltage
    LCD_Write_COM(0x00,0x13); LCD_Write_DATA(0x00,0x00); // VDV[4:0] for VCOM
amplitude
    LCD_Write_COM(0x00,0x07); LCD_Write_DATA(0x00,0x01);
    delayms(50); // Dis-charge capacitor power voltage
    LCD_Write_COM(0x00,0x10); LCD_Write_DATA(0x10,0x90); //SAP, BT[3:0], AP,
DSTB, SLP, STB
    LCD_Write_COM(0x00,0x11); LCD_Write_DATA(0x02,0x27); // DC1[2:0], DC0[2:0],

```

VC[2:0]

```
    delayms(50); // Delay 50ms
    LCD_Write_COM(0x00,0x12); LCD_Write_DATA(0x00,0x1F); // Internal reference
voltage= Vci;
    delayms(50); // Delay 50ms
    LCD_Write_COM(0x00,0x13); LCD_Write_DATA(0x15,0x00); //Set VDV[4:0] for
VCOM amplitude
    LCD_Write_COM(0x00,0x29); LCD_Write_DATA(0x00,0x27);
    LCD_Write_COM(0x00,0x2B); LCD_Write_DATA(0x00,0x0D); // Set Frame Rate
000C
    delayms(50); // Delay 50ms
    LCD_Write_COM(0x00,0x20); LCD_Write_DATA(0x00,0x00); // GRAM horizontal
Address
    LCD_Write_COM(0x00,0x21); LCD_Write_DATA(0x00,0x00); // GRAM Vertical
Address
// ----- Adjust the Gamma Curve -----
LCD_Write_COM(0x00,0x30); LCD_Write_DATA(0x00,0x00);
LCD_Write_COM(0x00,0x31); LCD_Write_DATA(0x07,0x07);
LCD_Write_COM(0x00,0x32); LCD_Write_DATA(0x03,0x07);
LCD_Write_COM(0x00,0x35); LCD_Write_DATA(0x02,0x00);
LCD_Write_COM(0x00,0x36); LCD_Write_DATA(0x00,0x08);
LCD_Write_COM(0x00,0x37); LCD_Write_DATA(0x00,0x04);
LCD_Write_COM(0x00,0x38); LCD_Write_DATA(0x00,0x00);
LCD_Write_COM(0x00,0x39); LCD_Write_DATA(0x07,0x07);
LCD_Write_COM(0x00,0x3C); LCD_Write_DATA(0x00,0x02);
LCD_Write_COM(0x00,0x3D); LCD_Write_DATA(0x1D,0x04);

//----- Set GRAM area -----
LCD_Write_COM(0x00,0x50); LCD_Write_DATA(0x00,0x00); // Horizontal GRAM
Start Address
LCD_Write_COM(0x00,0x51); LCD_Write_DATA(0x00,0xEF); // Horizontal GRAM
End Address
LCD_Write_COM(0x00,0x52); LCD_Write_DATA(0x00,0x00); // Vertical GRAM Start
Address
LCD_Write_COM(0x00,0x53); LCD_Write_DATA(0x01,0x3F); // Vertical GRAM Start
Address
LCD_Write_COM(0x00,0x60); LCD_Write_DATA(0xA7,0x00); // Gate Scan Line
LCD_Write_COM(0x00,0x61); LCD_Write_DATA(0x00,0x01); // NDL,VLE, REV
LCD_Write_COM(0x00,0x6A); LCD_Write_DATA(0x00,0x00); // set scrolling line
//----- Partial Display Control -----
LCD_Write_COM(0x00,0x80); LCD_Write_DATA(0x00,0x00);
LCD_Write_COM(0x00,0x81); LCD_Write_DATA(0x00,0x00);
LCD_Write_COM(0x00,0x82); LCD_Write_DATA(0x00,0x00);
LCD_Write_COM(0x00,0x83); LCD_Write_DATA(0x00,0x00);
```

```

LCD_Write_COM(0x00,0x84); LCD_Write_DATA(0x00,0x00);
LCD_Write_COM(0x00,0x85); LCD_Write_DATA(0x00,0x00);
//----- Panel Control -----
LCD_Write_COM(0x00,0x90); LCD_Write_DATA(0x00,0x10);
LCD_Write_COM(0x00,0x92); LCD_Write_DATA(0x06,0x00);
LCD_Write_COM(0x00,0x07); LCD_Write_DATA(0x01,0x33); // 262K color and
display ON
LCD_CS =1; //disable cs

}

}

```

**Second, build the function to calculate the address:**

```

void Address_set(unsigned int x1,unsigned int y1,unsigned int x2,unsigned int y2)
{
    LCD_Write_COM(0x00,0x20);LCD_Write_DATA(x1>&gt;8,x1);
    LCD_Write_COM(0x00,0x21);LCD_Write_DATA(y1>&gt;8,y1);
    LCD_Write_COM(0x00,0x50);LCD_Write_DATA(x1>&gt;8,x1);
    LCD_Write_COM(0x00,0x52);LCD_Write_DATA(y1>&gt;8,y1);
    LCD_Write_COM(0x00,0x51);LCD_Write_DATA(x2>&gt;8,x2);
    LCD_Write_COM(0x00,0x53);LCD_Write_DATA(y2>&gt;8,y2);
    LCD_Write_COM(0x00,0x22);
}

```

**Third, build the function to send data/command into data bus:**

```

void LCD_Write_COM(char VH,char VL) //snet command
{
    LCD_RS=0;
    LCD_Writ_Bus(VH,VL);
}

void LCD_Write_DATA(char VH,char VL)//sent data
{
    LCD_RS=1;
    LCD_Writ_Bus(VH,VL);
}

void LCD_Writ_Bus(char VH,char VL) //Write Data
{
    LCD_DataPortH=VH;
    LCD_DataPortL=VL;
    LCD_WR=0;
    LCD_WR=1;
}

```

```
}
```

#### **Fourth, build a clean screen function:**

```
void Pant(char VH,char VL)
{
    int i,j;
    LCD_CS =0;
    Address_set(0,0,240,320);
    for(i=0;i<320;i++)
    {
        for (j=0;j<240;j++)
        {
            LCD_Write_DATA(VH,VL);
        }
    }
    LCD_CS =1;
}
```

#### **Last, the main loop , display the image:**

```
main()
{
    int i,j,k;
    LCD_Init();          //TFT initial
    Pant(0xff,0xff); // clean screen
    LCD_CS =0;
    for(k=0;k<8;k++) //display
    {
        for(j=0;j<6;j++)
        {
            Address_set(40*j,40*k,40*j+39,40*k+39);
            for(i=0;i<1600;i++)
            {
                LCD_Write_DATA(image[i*2+1],image[i*2]);
            }
        }
    }
    LCD_CS =1;
    while(1)
    {
        LCD_Init();
        Pant(0xff,0xff);
```

```

LCD_CS =0;
for(k=0;k<8;k++)
{
    for(j=0;j<6;j++)
    {
        Address_set(40*j,40*k,40*j+39,40*k+39);
        for(i=0;i<1600;i++)
        {
            LCD_Write_DATA(image[i*2+1],image[i*2]);
        }
    }
}
LCD_CS =1;
delayms(1000);
}
}

```

### 3、8Bit Mode Demo

We have showed how to use the Arduino control the module for refreshing the screen , but the demo is in 16 bit mode , we received some E-mail require the 8 Bit mode demo, so we now publish the new demo which using the Arduino to control the module display a picture in 8 bit mode.

#### **The connection is:**

DB8 – DB15 to D0 – D7 of Arduino ; DB0 – DB8 to GND  
RS to D8 ; WR to D9 ; RD to 3.3V  
CS to D10 ; RESET to D11 ; LDEA to 3.3V  
VCC to 5V; GND to GND

Download the code below into Arduino :

```

#include <avr/pgmspace.h>

#define LCD_RS 8
#define LCD_WR 9
#define LCD_CS 10
#define LCD_REST 11

extern unsigned char image[3200];

```

```

void LCD_Writ_Bus(char VH,char VL)
{
    unsigned char i,temp,data;
    data=VH;
    for(i=0;i<8;i++)
    {
        temp=(data&0x01);
        if(temp)
            digitalWrite(i,HIGH);
        else
            digitalWrite(i,LOW);
        data=data>>1;
    }
    digitalWrite(LCD_WR,LOW);
    digitalWrite(LCD_WR,HIGH);
    data=VL;
    for(i=0;i<8;i++)
    {
        temp=(data&0x01);
        if(temp)
            digitalWrite(i,HIGH);
        else
            digitalWrite(i,LOW);
        data=data>>1;
    }
    digitalWrite(LCD_WR,LOW);
    digitalWrite(LCD_WR,HIGH);
}

```

```

void LCD_Write_COM(char VH,char VL) //send order
{
    digitalWrite(LCD_RS,LOW);
    LCD_Writ_Bus(VH,VL);
}

```

```

void LCD_Write_DATA(char VH,char VL) //send data
{
    digitalWrite(LCD_RS,HIGH);
    LCD_Writ_Bus(VH,VL);
}

```

```

void Address_set(unsigned int x1,unsigned int y1,unsigned int x2,unsigned int y2)

```

```

{
    LCD_Write_COM(0x00,0x20);
    LCD_Write_DATA(x1>>8,x1);
    LCD_Write_COM(0x00,0x21);
    LCD_Write_DATA(y1>>8,y1);
    LCD_Write_COM(0x00,0x50);
    LCD_Write_DATA(x1>>8,x1);
    LCD_Write_COM(0x00,0x52);
    LCD_Write_DATA(y1>>8,y1);
    LCD_Write_COM(0x00,0x51);
    LCD_Write_DATA(x2>>8,x2);
    LCD_Write_COM(0x00,0x53);
    LCD_Write_DATA(y2>>8,y2);
    LCD_Write_COM(0x00,0x22);
}

void LCD_Init(void)
{
    digitalWrite(LCD_REST,HIGH);
    delay(5);
    digitalWrite(LCD_REST,LOW);
    delay(5);
    digitalWrite(LCD_REST,HIGH);
    delay(5);

    digitalWrite(LCD_CS,LOW);
    //***** Start Initial Sequence *****/
    LCD_Write_COM(0x00,0xE5);
    LCD_Write_DATA(0x78,0xF0); // set SRAM internal timing
    LCD_Write_COM(0x00,0x01);
    LCD_Write_DATA(0x01,0x00); // set SS and SM bit
    LCD_Write_COM(0x00,0x02);
    LCD_Write_DATA(0x07,0x00); // set 1 line inversion
    LCD_Write_COM(0x00,0x03);
    LCD_Write_DATA(0x10,0x30); // set GRAM write direction and BGR=1.
    LCD_Write_COM(0x00,0x04);
    LCD_Write_DATA(0x00,0x00); // Resize register
    LCD_Write_COM(0x00,0x08);
    LCD_Write_DATA(0x02,0x07); // set the back porch and front porch
    LCD_Write_COM(0x00,0x09);
    LCD_Write_DATA(0x00,0x00); // set non-display area refresh cycle ISC[3:0]
    LCD_Write_COM(0x00,0x0A);
    LCD_Write_DATA(0x00,0x00); // FMARK function
}

```

```

LCD_Write_COM(0x00,0x0C);
LCD_Write_DATA(0x00,0x00); // RGB interface setting
LCD_Write_COM(0x00,0x0D);
LCD_Write_DATA(0x00,0x00); // Frame marker Position
LCD_Write_COM(0x00,0x0F);
LCD_Write_DATA(0x00,0x00); // RGB interface polarity
//*****Power On sequence *****/
LCD_Write_COM(0x00,0x10);
LCD_Write_DATA(0x00,0x00); // SAP, BT[3:0], AP, DSTB, SLP, STB
LCD_Write_COM(0x00,0x11);
LCD_Write_DATA(0x00,0x07); // DC1[2:0], DC0[2:0], VC[2:0]
LCD_Write_COM(0x00,0x12);
LCD_Write_DATA(0x00,0x00); // VREG1OUT voltage
LCD_Write_COM(0x00,0x13);
LCD_Write_DATA(0x00,0x00); // VDV[4:0] for VCOM amplitude
LCD_Write_COM(0x00,0x07);
LCD_Write_DATA(0x00,0x01);
delay(50); // Dis-charge capacitor power voltage
LCD_Write_COM(0x00,0x10);
LCD_Write_DATA(0x10,0x90); // 1490//SAP, BT[3:0], AP, DSTB, SLP, STB
LCD_Write_COM(0x00,0x11);
LCD_Write_DATA(0x02,0x27); // DC1[2:0], DC0[2:0], VC[2:0]
delay(50); // Delay 50ms
LCD_Write_COM(0x00,0x12);
LCD_Write_DATA(0x00,0x1F); //001C// Internal reference voltage= Vci;
delay(50); // Delay 50ms
LCD_Write_COM(0x00,0x13);
LCD_Write_DATA(0x15,0x00); //0x1000//1400      Set VDV[4:0] for VCOM amplitude
1A00
LCD_Write_COM(0x00,0x29);
LCD_Write_DATA(0x00,0x27); //0x0012 //001a   Set VCM[5:0] for VCOMH  //0x0025
0034
LCD_Write_COM(0x00,0x2B);
LCD_Write_DATA(0x00,0x0D); // Set Frame Rate    000C
delay(50); // Delay 50ms
LCD_Write_COM(0x00,0x20);
LCD_Write_DATA(0x00,0x00); // GRAM horizontal Address
LCD_Write_COM(0x00,0x21);
LCD_Write_DATA(0x00,0x00); // GRAM Vertical Address
// ----- Adjust the Gamma Curve -----//
LCD_Write_COM(0x00,0x30);
LCD_Write_DATA(0x00,0x00);
LCD_Write_COM(0x00,0x31);
LCD_Write_DATA(0x07,0x07);

```

```

LCD_Write_COM(0x00,0x32);
LCD_Write_DATA(0x03,0x07);
LCD_Write_COM(0x00,0x35);
LCD_Write_DATA(0x02,0x00);
LCD_Write_COM(0x00,0x36);
LCD_Write_DATA(0x00,0x08); //0207
LCD_Write_COM(0x00,0x37);
LCD_Write_DATA(0x00,0x04); //0306
LCD_Write_COM(0x00,0x38);
LCD_Write_DATA(0x00,0x00); //0102
LCD_Write_COM(0x00,0x39);
LCD_Write_DATA(0x07,0x07); //0707
LCD_Write_COM(0x00,0x3C);
LCD_Write_DATA(0x00,0x02); //0702
LCD_Write_COM(0x00,0x3D);
LCD_Write_DATA(0x1D,0x04); //1604

//----- Set GRAM area -----
LCD_Write_COM(0x00,0x50);
LCD_Write_DATA(0x00,0x00); // Horizontal GRAM Start Address
LCD_Write_COM(0x00,0x51);
LCD_Write_DATA(0x00,0xEF); // Horizontal GRAM End Address
LCD_Write_COM(0x00,0x52);
LCD_Write_DATA(0x00,0x00); // Vertical GRAM Start Address
LCD_Write_COM(0x00,0x53);
LCD_Write_DATA(0x01,0x3F); // Vertical GRAM Start Address
LCD_Write_COM(0x00,0x60);
LCD_Write_DATA(0xA7,0x00); // Gate Scan Line
LCD_Write_COM(0x00,0x61);
LCD_Write_DATA(0x00,0x01); // NDL,VLE, REV
LCD_Write_COM(0x00,0x6A);
LCD_Write_DATA(0x00,0x00); // set scrolling line
//----- Partial Display Control -----
LCD_Write_COM(0x00,0x80);
LCD_Write_DATA(0x00,0x00);
LCD_Write_COM(0x00,0x81);
LCD_Write_DATA(0x00,0x00);
LCD_Write_COM(0x00,0x82);
LCD_Write_DATA(0x00,0x00);
LCD_Write_COM(0x00,0x83);
LCD_Write_DATA(0x00,0x00);
LCD_Write_COM(0x00,0x84);
LCD_Write_DATA(0x00,0x00);
LCD_Write_COM(0x00,0x85);

```

```

LCD_Write_DATA(0x00,0x00);
//----- Panel Control -----//
LCD_Write_COM(0x00,0x90);
LCD_Write_DATA(0x00,0x10);
LCD_Write_COM(0x00,0x92);
LCD_Write_DATA(0x06,0x00);
LCD_Write_COM(0x00,0x07);
LCD_Write_DATA(0x01,0x33); // 262K color and display ON
digitalWrite(LCD_CS,HIGH);

}

void Pant(char VH,char VL)
{
int i,j;
digitalWrite(LCD_CS,LOW);
Address_set(0,0,240,320);
for(i=0;i<320;i++)
{
    for (j=0;j<240;j++)
    {
        LCD_Write_DATA(VH,VL);
    }
}
digitalWrite(LCD_CS,HIGH);
}

void setup()
{
unsigned char p;
char hi,lo;
int i,j,k;
for(p=0;p<20;p++)
{
    pinMode(p,OUTPUT);
}

LCD_Init();
// Pant(0xff,0xff);

digitalWrite(LCD_CS,LOW);
for(k=0;k<8;k++)
{

```

```

for(j=0;j<6;j++)
{
    Address_set(40*j,40*k,40*j+39,40*k+39);
    for(i=0;i<1600;i++)
    {
        hi=pgm_read_byte(&image[i*2+1]);
        lo=pgm_read_byte(&image[i*2]);
        LCD_Write_DATA(hi,lo);

    }
}
}
digitalWrite(LCD_CS,HIGH);
}

void loop()
{
}

```

Reset the Arduino board , you will see the screen full with the picture that in image[3200] .

## 4、Touch Screen Handwrite Demo

Today we show a demo that use the Arduino to control the module 4 display, and used the touch screen to achieve handwrite function.

The LCD connection is the same as that in “3、8Bit Mode Demo”, and the touch screen connection is :

DCLK to D14(A0) pin of Arduino  
 CS to D15(A1) pin of Arduino  
 DIN to D16(A2) pin of Arduino  
 DOUT to D18(A4) pin of Arduino  
 IRQ to D19(A5) pin of Arduino

The display code is the same as we have released , now we just give a brief introduction of SPI and touch IC control.

### SPI Start:

```

void spistar()
{
    digitalWrite(CS,HIGH);

```

```
    digitalWrite(DCLK,HIGH);
    digitalWrite(DIN,HIGH);
    digitalWrite(DCLK,HIGH);
}
```

### **SPI Write Data function:**

```
void WriteCharTo7843(unsigned char num)
{
    unsigned char count=0;
    unsigned char temp;
    unsigned nop;
    temp=num;
    digitalWrite(DCLK,LOW);
    for(count=0;count<8;count++)
    {
        if(temp&amp;0x80)
            digitalWrite(DIN,HIGH);
        else
            digitalWrite(DIN,LOW);

        temp=temp<<1;

        digitalWrite(DCLK,LOW);
        nop++;
        nop++;
        digitalWrite(DCLK,HIGH);
        nop++;
        nop++;
    }
}
```

### **SPI Read Data function:**

```
unsigned int ReadFromCharFrom7843()
{
    unsigned nop;
    unsigned char count=0;
    unsigned int Num=0;
    for(count=0;count<12;count++)
    {
        Num<<=1;
```

```
digitalWrite(DCLK,HIGH);//DCLK=1; _nop_();_nop_();_nop_();
nop++;
digitalWrite(DCLK,LOW);//DCLK=0; _nop_();_nop_();_nop_();
nop++;
if(digitalRead(DOUT)) Num++;
}
return(Num);
}
```

### **Get coordinates:**

```
void AD7843(void)
{
    digitalWrite(CS,LOW);
    WriteCharTo7843(0x90);
    digitalWrite(DCLK,HIGH);
    digitalWrite(DCLK,LOW);
    TP_Y=ReadFromCharFrom7843();
    WriteCharTo7843(0xD0);
    digitalWrite(DCLK,HIGH);
    digitalWrite(DCLK,LOW);
    TP_X=ReadFromCharFrom7843();
    digitalWrite(CS,HIGH);
}
```